Validation Report

California, SPS-2 Task Order 16, CLIN 2 March 25 to 26, 2008

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1 Executive Summary

A visit was made to the California 0200 on March 25 to 26, 2008 for the purposes of conducting a validation of the WIM system located on SR 99, approximately 20 miles south of Modesto, CA. The SPS-2 is located in the righthand, northbound lane of a four-lane divided facility. The posted speed limit at this location is 55 mph. The LTPP lane is the only lane that is instrumented at this site. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This is the first validation visit to this location. The site was installed on November 30, 2007 by International Road Dynamics Inc..

This site demonstrates the ability to produce research quality loading data under the observed conditions. The classification data is also of research quality.

The site is instrumented with bending plate sensors and iSYNC electronics. It is installed in portland cement concrete.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 76,580 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 64,740 lbs., the "partial" truck.

The validation speeds ranged from 45 to 55 miles per hour. The pavement temperatures ranged from 35 to 79 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was also achieved.

Table 1-1 Post-Validation results – 060200 – 26-Mar-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.3 \pm 3.6\%$	Pass
Tandem axles	±15 percent	$1.3 \pm 2.7\%$	Pass
GVW	±10 percent	$1.2 \pm 1.4\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	0.0 ± 0.1 ft	Pass

Prepared: djw Checked: bko

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area.

Based on profile data collected at this site on December 17, 2007 WIMIndex values have been computed. All WIMIndex values fell between the Lower and Upper Thresholds.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 Results Based on ASTM E-1318-02 Test Procedures

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

This site needs five years of data to meet the goal of five years of research quality data.

2 Corrective Actions Recommended

There are no corrective actions required at this site at this time.

3 Post Calibration Analysis

This final analysis is based on test runs conducted March 26, 2008 during the morning and afternoon hours at test site 060200 on SR 99. This SPS-2 site is at milepost 32.5 on the northbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for the validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 76,580 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 64,740 lbs., the "partial" truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 45 to 55 miles per hour. The desired speed range was achieved during this validation. Payement surface temperatures were recorded during the test runs ranging from about 35 to 79 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

As shown in Table 3-1, this site met all LTPP requirements for research quality loading data.

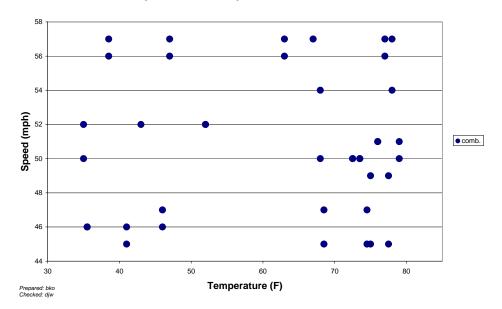
Table 3-1 Post-Validation Results – 060200 – 26-Mar-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.3 \pm 3.6\%$	Pass
Tandem axles	±15 percent	$1.3 \pm 2.7\%$	Pass
GVW	±10 percent	$1.2 \pm 1.4\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass
		Prepared: diw	Checked: bko

The test runs were conducted primarily during the late morning and early afternoon hours under sunny weather conditions, resulting in a wide range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the data set was split into three speed groups and two temperature groups. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the desired distribution of speed and temperature combinations was achieved for this set of validation runs.

The three speed groups were divided as follows: Low speed -45 to 47 mph, Medium speed -48 to 52 mph and High speed -53 + mph. The two temperature groups were created by splitting the runs between those at 35 to 55 degrees Fahrenheit for Low temperature and 56 to 79 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations



Figure~3-1~Post-Validation~Speed-Temperature~Distribution-060200-26-Mar-2008

A series of graphs were developed to investigate visually any sign of a relationship between speed or temperature and the scale performance.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. It can be seen that the GVW is slightly overestimated by the WIM equipment over the entire speed range. The scatter of error is consistent over the entire speed range.

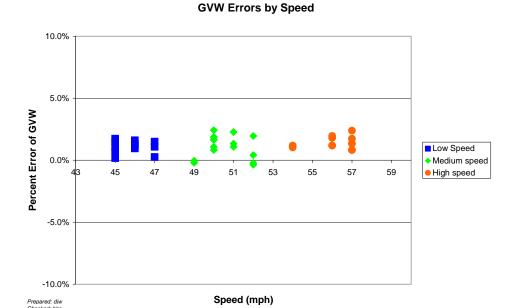


Figure 3-2 Post-validation GVW Percent Error vs. Speed – 060200 – 26-Mar-2008

Figure 3-3 shows the relationship between temperature and GVW percentage error. The graph illustrates that there does not appear to be a relationship between GVW error and pavement temperature. This figure shows the gap in the temperature range that led to the decision to create two temperature groups rather than three.

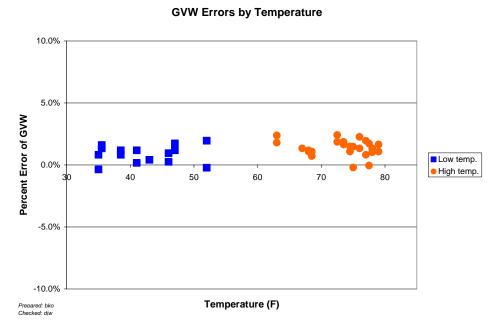


Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 060200 – 26-Mar-2008

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. Axle spacing errors appear to be consistent throughout the test truck speed range and are limited to about 1.2 inches (0.1 feet). Vehicle speeds appear to have no effect on the error of measured axle spacing.

0.2 0.15 0.1 0.05 0.2 43 45 47 49 51 53 55 57 59 Speed/space

Drive Tandem Spacing vs. WIM Speed

Figure 3-4 Post-Validation Spacing vs. Speed – 060200 – 26-Mar-2008

3.1 Temperature-based Analysis

Prepared: diw Checked: bko

The two temperature groups were created by splitting the runs between those at 35 to 55 degrees Fahrenheit for Low temperature and 56 to 79 degrees Fahrenheit for High temperature.

Speed (mph)

Table 3-2 Post-Validation Results by Temperature Bin – 060200 – 26-Mar-2008

Element	95%	Low	High
	Limit	Temperature 35 to 55 °F	Temperature 56 to 79 °F
Steering axles	<u>+</u> 20 %	$0.8 \pm 3.5\%$	$0.0 \pm 3.8\%$
Tandem axles	<u>+</u> 15 %	$0.9 \pm 2.8\%$	$1.6 \pm 2.6\%$
GVW	<u>+</u> 10 %	$0.9 \pm 1.5\%$	$1.4 \pm 1.3\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

From Table 3-2, it appears that changes in temperature do not significantly affect mean errors of GVW, Tandem, or Steering axle weight estimates. The scatter of errors remains constant throughout the entire temperature range.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph.

GVW estimation appears to be reasonably consistent over the entire temperature range for the population as a whole. The GVW results for both the Golden Truck (squares) and the partially loaded truck (diamonds) indicate similar results for both mean error and scatter.

GVW Errors vs. Temperature by Truck

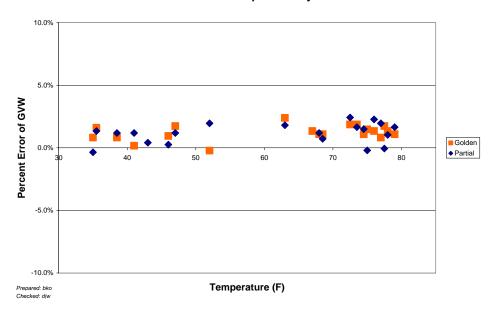


Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 060200 – 26-Mar-2008

Figure 3-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. The figure illustrates the ability of the equipment to accurately estimate steering axle weights at all temperatures. The scatter of error appears to be slightly greater at the higher temperatures.

Steering Axle Errors vs. Temperature

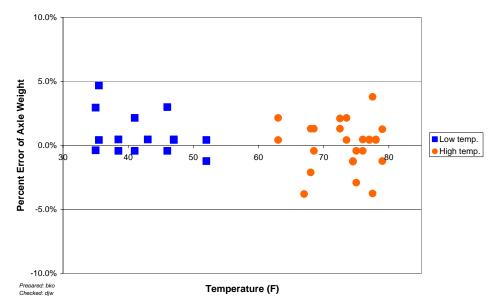


Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group $-\,060200$ $-\,26\text{-Mar-}2008$

3.2 Speed-based Analysis

The three speed groups were divided using 45 to 47 mph for Low speed, 48 to 52 mph for Medium speed and 53+ mph for High speed.

Table 3-3 Post-Validation Results by Speed Bin – 060200 – 26-Mar-2008

Element	95%	Low	Medium	High
	Limit	Speed	Speed	Speed
		45 to 47 mph	48 to 52 mph	53+ mph
Steering axles	<u>+</u> 20 %	$0.9 \pm 4.5\%$	$0.0 \pm 4.0\%$	$0.2 \pm 3.1\%$
Tandem axles	<u>+</u> 15 %	$1.0 \pm 2.9\%$	$1.3 \pm 2.7\%$	$1.7 \pm 2.9\%$
GVW	<u>+</u> 10 %	$1.1 \pm 1.1\%$	$1.1 \pm 2.0\%$	$1.4 \pm 1.1\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 3-3, it appears that the equipment estimates all weights with reasonable accuracy at all speeds. Scatter for Tandem axles and GVW errors are consistent over the entire speed range. Scatter of Steering axle weight errors slightly decrease as speed increases.

Figure 3-7 illustrates the accuracy of the equipment in estimating GVW for the truck population as a whole as well as for each truck individually. The range of error for the trucks combined and individually is also consistent over the entire speed range.

GVW Errors vs. Speed

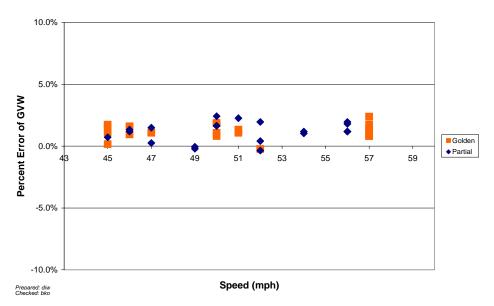


Figure 3-7 Post-Validation GVW Percent Error vs. Speed by Truck – 060200 – 26-Mar-2008

Figure 3-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for auto-calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. The figure shows how the WIM equipment estimates steering axle weights with reasonable accuracy at all speeds.

Steering Axle Errors vs. Speed

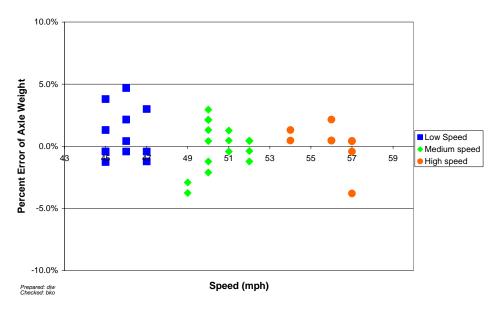


Figure 3-8 Post-Validation Steering Axle Percent Error vs. Speed by Group -060200-26-Mar-2008

3.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 3-4 has the classification error rates by class. The overall misclassification rate is zero percent.

Table 3-4 Truck Misclassification Percentages for 060200 – 26-Mar-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	0	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	N/A	13	N/A

Prepared: djw Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 3-5 Truck Classification Mean Differences for 060200 – 26-Mar-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	0	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	N/A	13	N/A

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were

seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. Since the classification data met research quality standards, the observed bias and variability are thought to be more strongly related to radar speed precision than errors in the WIM equipment.

3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

4 Pavement Discussion

The pavement condition did not appear to influence truck movement across the sensors.

4.1 Profile Analysis

The WIM site is a section of pavement that is 305 meters long with the WIM scale located at 274.5 meters from the beginning of the test section. An ICC profiler was used to collected longitudinal profiles of the test section with a sampling interval of 25 mm.

Profile data collected at the SPS WIM location by Nichols Consulting Engineers on December 17, 2007 were processed through the LTPP SPS WIM Index Software version 1.1. This WIM scale is installed on rigid pavement.

A total of 8 profiler passes were conducted over the WIM Site. Since the issuance of the LTPP directive on collection of longitudinal profile data for SPS WIM sections, the requirements have been a minimum of 3 passes in the center of the lane and one shifted to each side. For this site, the RSC has completed 4 passes at the center of the lane, 2 passes shifted to the left side of the lane, and 2 passes shifted to the right side of the lane. Shifts to the sides of the lane were collected as close to the lane edge as was safely possible. For each profiler pass, profiles were collected under the left wheel path (LWP) and the right wheel path (RWP).

The SPS WIM Index software was developed with four different indices: LRI, SRI, Peak LRI, and Peak SRI. The LRI incorporates the pavement profile starting 25.8 m prior to the scale and ending 3.2 m after the scale in the direction of travel. The SRI incorporates a shorter section of pavement profile beginning 2.74 m prior to the WIM scale and ending 0.46 m after the scale. The LRI and SRI are the index values for the actual location of the WIM scale. Peak LRI is the highest value of the LRI within 30 m prior to the scale. Peak SRI indicates the highest value of SRI that is located between 2.45 m prior to the scale and 1.5 m after the scale. Also, a range for each of the indices was developed to provide the smoothness criteria. The ranges are shown in Table 4-1. When all of the values are below the lower thresholds, it is presumed unlikely that the pavement smoothness will significantly influence sensor output. When one or more values exceed an upper threshold, there is a reasonable expectation that the pavement smoothness will influence the outcome of the validation. When all values are below the upper threshold but not all below the lower threshold, the pavement smoothness may or may not influence the validation outcome.

Table 4-1 Thresholds for WIM Index Values

Index	Lower Threshold (m/km)	Upper Threshold (m/km)
LRI	0.50	2.1
SRI	0.50	2.1
Peak LRI	0.50	2.1
Peak SRI	0.75	2.9

Prepared: als Checked: jrn

Table 4-2 shows the computed index values for all 8 profiler passes for this WIM site. The average values over the passes in each path were also calculated when three or more passes were completed. These are shown in the rightmost column of the table. Values above the upper index limits are presented in bold while values below the lower index limits are presented in italics.

Table 4-2 WIM Index Values - 060200 - 17-Dec-2007

Profile	r Passes	<u> </u>	Pass 1	Pass 2	Pass 3	Pass 4	Ave.
Center	LWP	LRI (m/km)	1.085	1.021	1.063	1.078	1.062
		SRI (m/km)	0.974	1.358	0.952	0.628	0.978
		Peak LRI (m/km)	1.093	1.120	1.081	1.308	1.150
		Peak SRI (m/km)	1.217	1.620	1.125	1.057	1.255
	RWP	LRI (m/km)	1.214	1.278	1.300	1.064	1.214
		SRI (m/km)	1.381	1.427	1.445	0.904	1.289
		Peak LRI (m/km)	1.216	1.281	1.301	1.077	1.219
		Peak SRI (m/km)	1.594	1.449	1.638	1.241	1.480
Left	LWP	LRI (m/km)	1.218	1.191			
Shift		SRI (m/km)	1.209	0.765			
		Peak LRI (m/km)	1.419	1.548			
		Peak SRI (m/km)	1.452	0.996			
	RWP	LRI (m/km)	1.137	1.413			
		SRI (m/km)	1.318	1.827			
		Peak LRI (m/km)	1.137	1.416			
		Peak SRI (m/km)	1.363	1.917			
Right	LWP	LRI (m/km)	1.147	0.875			
Shift		SRI (m/km)	0.571	0.778			
		Peak LRI (m/km)	1.173	0.892			
		Peak SRI (m/km)	0.988	0.959			
	RWP	LRI (m/km)	1.173	1.123			
		SRI (m/km)	1.029	0.811			
		Peak LRI (m/km)	1.256	1.275			
		Peak SRI (m/km)	1.404	1.268			

Prepared: als Checked: jrn

From the table, it can be seen that all of the values fall between the threshold limits indicating that the pavement roughness may or may not interfere with the validation outcome.

4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement, no distresses that would influence truck movement across the WIM scales were noted.

4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires and any of the sensors for the equipment.

5 Equipment Discussion

The traffic monitoring equipment at this location includes bending plate sensors and iSYNC electronics. The sensors are installed in a portland cement concrete pavement.

5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the validation. All sensors and system components were found to be operating within acceptable tolerances.

5.2 Calibration Process

The equipment required no iterations of the calibration process between the initial 40 runs and the final 40 runs.

The operating system weight compensation parameters that were in place during the validation and remained afterward are as follows:

	Left	Right
	Sensor 1	Sensor 2
72 kph	3395	3395
80 kph	3395	3395
88 kph	3420	3420
96 kph	3360	3360
104 kph	3360	3360

5.3 Summary of Traffic Sheet 16s

Table 5-1 has the information for TRF_CALIBRATION_AVC from Sheet 16s submitted for the current visit. . We have no Sheet 16 information for the initial calibration for this site.

Table 5-1 Classification Validation History – 060200 – 26-Mar-2008

			Mean Difference				
Date	Method	Class 9	Class 8	Other 1	Other 2	Unclassified	
26-Mar-08	Manual	0	0			0	
25-Mar-08	Manual	0	0			0	

Prepared: djw Checked: bko

Table 5-2 has the information for TRF_CALIBRATION_WIM from Sheet 16s submitted for the current visit. We have no Sheet 16 information for the initial calibration for this site.

Table 5-2 Weight Validation History – 060200 – 26-Mar-2008

		Mean Error and (SD)			
Date	Method	GVW	Single Axles	Tandem Axles	
26-Mar-08	Test Trucks	1.2 (0.7)	0.3 (1.8)	1.3 (1.4)	
25-Mar-08	Test Trucks	1.1 (1.1)	1.2 (1.7)	1.0 (1.4)	

Prepared: djw Checked: bko

5.4 Projected Maintenance/Replacement Requirements

Under a separate contract with the Phase II Contractor, this site is to be visited semiannually for routine preventive equipment diagnostics and inspection.

No corrective actions are required at this time.

6 Pre-Validation Analysis

This pre-validation analysis is based on test runs conducted March 25, 2008 during the late morning and early afternoon hours at test site 060200 on SR 99. This SPS-2 site is at milepost 32.5 on the northbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 77,260 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 64,930 lbs., the "partial" truck.

For the initial validation, each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 44 to 55 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 52 to 97degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-1.

As shown in Table 6-1 this site passed all of the performance criteria for weight and spacing. As a result, it was determined that a calibration of the system was not necessary.

Table 6-1 Pre-Validation Results – 060200 – 25-Mar-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$1.2 \pm 3.5\%$	Pass
Tandem axles	±15 percent	$1.0 \pm 2.8\%$	Pass
GVW	±10 percent	$1.1 \pm 2.1\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: djw Checked: bko

The test runs were conducted primarily during the late morning and early afternoon hours under sunny weather condition, resulting in a wide range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and three temperature groups. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was achieved for this set of validation runs.

The three speed groups were divided into 44 to 47 mph for Low speed, 48 to 52 mph for Medium speed and 53+ mph for High speed. The three temperature groups were created by splitting the runs between those at 52 to 63 degrees Fahrenheit for Low temperature, 64 to 71 degrees Fahrenheit for Medium temperature and 72 to 97 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations 60 58 56 54 50 50 55 60 65 70 75 80 85 90 95 100

Figure 6-1 Pre-Validation Speed-Temperature Distribution – 060200 – 25-Mar-2008

Temperature (F)

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. The figure illustrates the ability to estimate GVW accurately at all speeds. Variability appears to be consistent over the entire speed range.

GVW Errors by Speed

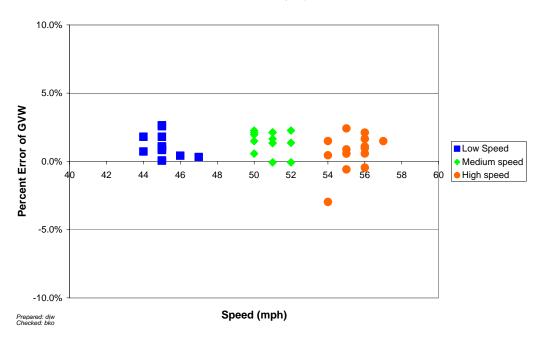


Figure 6-2 Pre-validation GVW Percent Error vs. Speed – 060200 – 25-Mar-2008

Figure 6-3 shows the lack of a relationship between temperature and GVW percentage error.

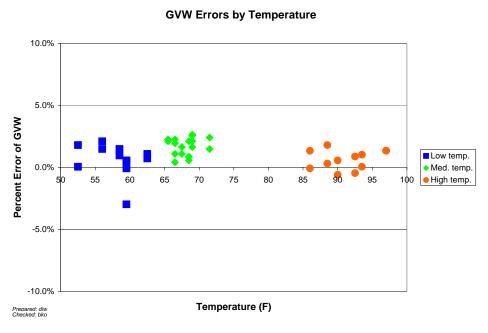


Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 060200 – 25-Mar-2008

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. The graph indicates that the errors in tandem spacings for the test trucks were not affected by changes in speed.

Figure 6-4 Pre-Validation Spacing vs. Speed - 060200 – 25-Mar-2008

6.1 Temperature-based Analysis

The three temperature groups were created by splitting the runs between those at 52 to 63 degrees Fahrenheit for Low temperature, 64 to 71 degrees Fahrenheit for Medium temperature and 72 to 97 degrees Fahrenheit for High temperature.

Table 6-2 Pre-Validation Results by Temperature Bin – 060200 – 25-Mar-2008

Element	95%	Low	Medium	High
	Limit	Temperature	Temperature	Temperature
		52 to 63 °F	64 to 71 °F	72 to 97 °F
Steering axles	<u>+</u> 20 %	$1.5 \pm 4.6\%$	$1.6 \pm 3.4\%$	$0.4 \pm 3.1\%$
Tandem axles	<u>+</u> 15 %	$0.5 \pm 3.2\%$	$1.7 \pm 2.6\%$	$0.6 \pm 2.2\%$
GVW	<u>+</u> 10 %	$0.6 \pm 2.9\%$	$1.7 \pm 1.5\%$	$0.6 \pm 1.7\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 6-2, it appears that the equipment estimates all weights with reasonable accuracy.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. The equipment appears to estimate GVW accurately at all temperatures for each truck and for the population as a whole. The variability in error for each truck appears to be similar at all temperatures and appears to be consistent for the truck population as a whole over the entire temperature range.

GVW Errors vs. Temperature by Truck

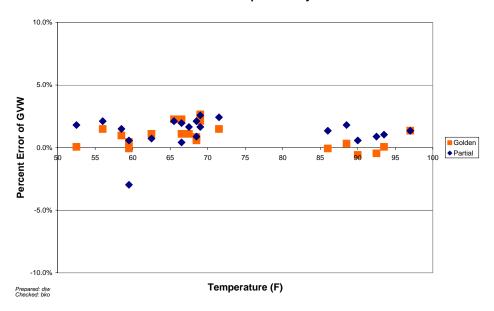


Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 060200 – 25-Mar-2008

Figure 6-6 shows the relationship between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for auto-calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. The figure shows that steering axle weights are slightly overestimated at the lower temperatures and estimated with reasonable accuracy at the higher temperatures.

page 20

Steering Axle Errors vs. Temperature

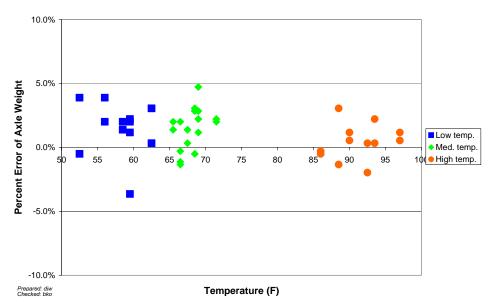


Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 060200 – 25-Mar-2008

6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -44 to 47 mph, Medium speed -48 to 52 mph and High speed -53+ mph.

Table 6-3 Pre-Validation Results by Speed Bin – 060200 – 25-Mar-2008

Element	95% Limit	Low Speed 44 to 47 mph	Medium Speed 48 to 52 mph	High Speed 53+ mph
Steering axles	<u>+</u> 20 %	$1.2 \pm 4.5\%$	$1.5 \pm 2.8\%$	$0.9 \pm 3.9\%$
Tandem axles	<u>+</u> 15 %	$1.1 \pm 2.7\%$	$1.4 \pm 2.0\%$	$0.6 \pm 3.6\%$
GVW	<u>+</u> 10 %	$1.1 \pm 1.8\%$	$1.5 \pm 1.7\%$	$0.7 \pm 2.9\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 6-3, it can be seen that the equipment generally estimates all weights and spacings accurately. Variability in error for all weights is slightly lower at the medium speeds.

Figure 6-2 illustrates the ability of the equipment to estimate GVW for both trucks with reasonable accuracy at all speeds. Variability in error appears to be similar for both trucks at all speeds.

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GVW Errors vs. Speed

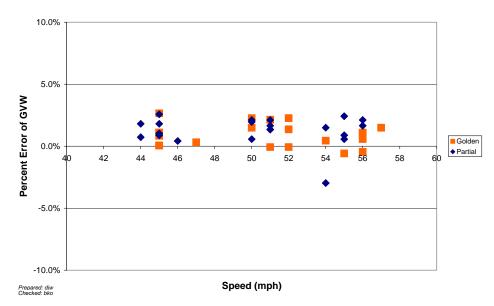


Figure 6-7 Pre-Validation GVW Percent Error vs. Speed Group - 060200 –25-Mar-2008

Figure 6-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. From the figure, it appears that the equipment overestimates steering axle weights at all speeds. Variability in error appears to remain fairly constant over the entire speed range, with a slight increase at the high speeds.

Steering Axle Errors vs. Speed

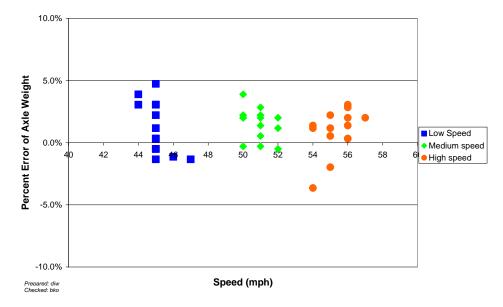


Figure 6-8 Pre-Validation Steering Axle Percent Error vs. Speed Group - 060200 – 25-Mar-2008

6.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-4 has the classification error rates by class. The overall misclassification rate is zero percent.

Table 6-4 Truck Misclassification Percentages for 060200 – 25-Mar-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	0
11	0	12	N/A	13	N/A

Prepared: djw Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them a re matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-5 Truck Classification Mean Differences for 060200 – 25-Mar-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	0
11	0	12	N/A	13	N/A

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over- or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. Since the classification data met research quality standards, the observed bias and variability are thought to be more strongly related to radar speed precision than errors in the WIM equipment.

6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

7 Data Availability and Quality

As of March 25, 2008 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

This site is a new installation. Therefore, there is no historical data for this site and 5 years of data is needed to meet the goal of a minimum of 5 years of research quality data.

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Class 9s and Class 5s constitute more than 10 percent of the truck population. Based on the data collected following this validation the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the Regional Support Contractor on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-1 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-1 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.

- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.
- o For all other trucks the typical axle configuration is used to determine the maximum allowable weight based on 18,000 pounds for single axles and 34,000 pounds for tandem axles. A ten percent cushion above that maximum is used to set the overweight threshold.
- o For all other trucks in the absence of site specific information the computation of under weights assumes the power unit weighs 10,000 pounds and each axle on a trailer 5,000 pounds. Ninety percent of the total for the unloaded configuration is the value below which a truck is considered under weight.
- o For all trucks other than class 9s that have a bi-modal distribution the unloaded peak is defined to be in a bin less than or equal to half of the allowable maximum weight.
- o For all trucks other than class 9s that have a bi-modal distribution the loaded peak is defined to be in a bin greater than or equal to half of the allowable maximum weight.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-1 GVW Characteristics of Major sub-groups of Trucks - 060200 - 26-Mar-2008

Characteristic	Class 9	Class 5
Percentage Overweights	0.0%	0.1%
Percentage Underweights	0.1%	0.1%
Unloaded Peak	32,000 lbs	
Loaded Peak	78,000 lbs	
Peak		8,000 lbs

Prepared: djw Checked: bko

The expected percentage of unclassified vehicles is 1.7%. This is based on the percentage of unclassified vehicles in the post-validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-4. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the Post-Validation period.

Class 5 GVW Distribution

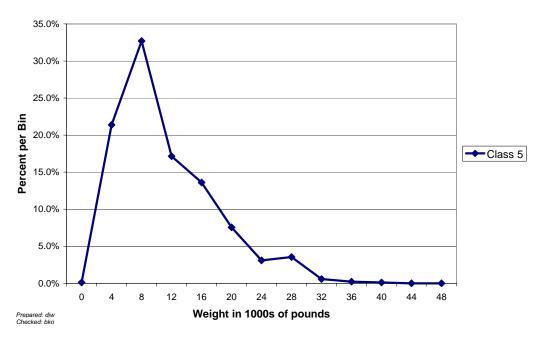


Figure 7-1 Expected GVW Distribution Class 5 – 060200 – 26-Mar-2008



Class 9 GVW Distribution

Percent per Bin 12.0% 10.0% Class 9 8.0% 6.0% 4.0% 2.0% 0 8 12 16 20 24 28 32 36 40 44 48 52 56 60 64 68 72 76 80 84 88 92 Weight in 1000s of pounds

Figure 7-2 Expected GVW Distribution Class 9 – 060200 – 26-Mar-2008

Vehicle Distribution Trucks (4-15)

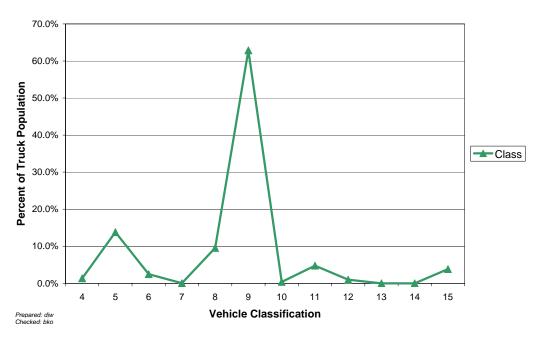


Figure 7-3 Expected Vehicle Distribution – 060200 – 26-Mar-2008

Speed Distribution For Trucks

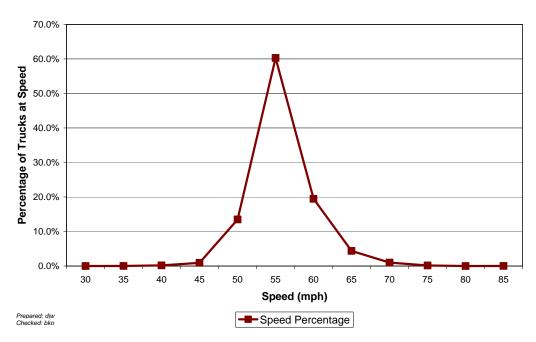


Figure 7-4 Expected Speed Distribution – 060200 – 26-Mar-2008

8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

```
Sheet 19 – Truck 1 – 3S2 loaded air suspension (3 pages)
Sheet 19 – Truck 2 – 3S2 partially loaded air suspension (3 pages)
Sheet 20 – Classification and Speed verification – pre-validation (2 pages)
Sheet 20 – Classification and Speed verification – post-validation (2 pages)
Sheet 21 – Pre-validation (3 pages)
Sheet 21 – Post-validation (3 pages)
Test Truck Photographs (6 pages)

LTPP Mod 3 Classification Scheme (1 page)
Final System Parameters (1 page)
```

9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following this page. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

11 Traffic Sheet 16(s)

Sheet 16s for the pre-validation and post-validation conditions are attached following the current Sheet 18 information at the very end of the report.

POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

STATE: California

SHRP ID: 060200

1.	General Information	3
2.	Contact Information	3
3.	Agenda	3
	Site Location/ Directions	
5.	Truck Route Information	5
6.	Sheet 17 – California (060200)	6

Figures

Figure 4-1 – Site 060200 in California	1
Figure 5-1 - Truck Scale Location for 060200	5
Figure 5-2 – Truck Route at 060200 in California	
Figure 6-1 – Site Map of 060200 in California)
Photos	
Photo 1 06_0200_Upstream_03_25_2008 .jpg)
Photo 2 06_0200_Downstream_03_25_2008.jpg)
Photo 3 06_0200_Solar_Panel_03_25_2008.jpg11	1
Photo 4 06_0200_Solar_Power_Box_03_25_2008.jpg11	1
Photo 5 06_0200_Cell_Modem_03_25_2008.jpg	2
Photo 6 06_0200_Cabinet_Exterior_03_25_2008.jpg	2
Photo 7 06_0200_Cabinet_Interior_Front_03_25_2008.jpg	3
Photo 8 06_0200_Cabinet_Interior_Rear_03_25_2008.jpg	
Photo 9 06_0200_Leading_Loop_03_25_2008.jpg14	
Photo 10 06_0200_Leading_WIM_Sensor_03_25_2008.jpg	
Photo 11 06_0200_Trailing_WIM_Sensor_03_25_2008.jpg	
Photo 12 06_0200_Trailing_Loop_03_25_2008.jpg	

Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites

1. General Information

SITE ID: 060200

LOCATION: SR 99, milepost 32.5, near Delhi, CA

VISIT DATE: March 25, 2008

VISIT TYPE: Validation

2. Contact Information

POINTS OF CONTACT:

Validation Team Leader: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

Highway Agency: Joe Avis, 916-654-3072, joe.avis@dot.ca.gov

Nick Burmas, 916-324-2906, nick.burmas@dot.ca.gov

Alfredo Rodriguez, 916-324-2244, alfredo_b_rodriguez@dot.ca.gov

FHWA COTR: Debbie Walker, 202-493-3068, deborah.walker@fhwa.dot.gov

FHWA Division Office Liaison:

Jason Dietz, 916-498-5886, jason.dietz@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

3. Agenda

BRIEFING DATE: *No briefing requested for this visit.*

ON SITE PERIOD: March 25 and 26, 2008

TRUCK ROUTE CHECK: Completed

4. Site Location/ Directions

NEAREST AIRPORT: San Jose International Airport, San Jose, CA (approximately 100 miles from the site)

DIRECTIONS TO THE SITE: SR 99, approximately 20 miles south of Modesto.

MEETING LOCATION: On site at 9:00 am, March 25, 2008.

WIM SITE LOCATION: *SR 99, milepost32.5; GPS = N 37.4160°, W -120.7580°*.

WIM SITE LOCATION MAP: See Figure 4.1

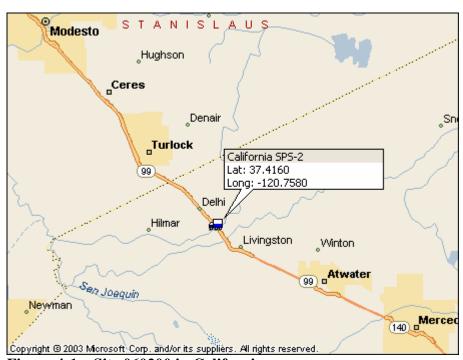


Figure 4-1 – Site 060200 in California

5. Truck Route Information

ROUTE RESTRICTIONS: None

CERTIFIED SCALE LOCATION: CAT Scales located at TA Livingston, SR 99 at Winton Parkway exit, Livingston, CA; GPS = 37.38888° N, -120.7363. See Figure 5.1

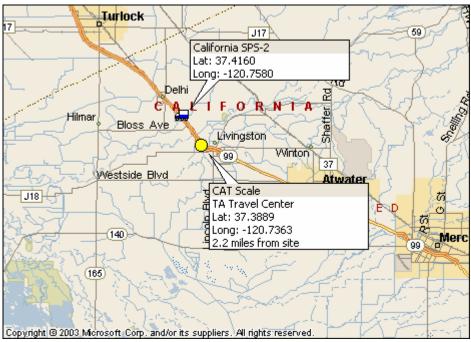


Figure 5-1 - Truck Scale Location for 060200

TRUCK ROUTE: See Figure 5.2



Figure 5-2 – Truck Route at 060200 in California

6.	Sheet 17 – California (060200)	
1.*	ROUTE <u>SR 99</u> MILEPOST <u>32.5</u> LTPP DIRECTION - <u>N</u> S E W	
2.*	WIM SITE DESCRIPTION - Grade<1 % Sag vertical Y / N Nearest SPS section upstream of the site	
3.*	LANE CONFIGURATION Lanes in LTPP direction2 Lane width1_2_ ft	
	Median - 1 - painted Shoulder - 1 - curb and gutter 2 - physical barrier 2 - paved AC 3 - paved PCC 4 - unpaved 5 - none	
	Shoulder width11ft	
4.*	PAVEMENT TYPEportland cement concrete	
I I	PAVEMENT SURFACE CONDITION – Distress Survey Date 3/25/2008 Photo Filename: 06 0200 Upstream 03 25 2008 jpg Date 3/25/2008 Photo Filename: 06 0200 Downstream 03 25 2008 jpg Date Photo Filename:	
6. *	SENSOR SEQUENCELoop – Bending Plate – Bending Plate -Loop	_
7. *	REPLACEMENT AND/OR GRINDING / / REPLACEMENT AND/OR GRINDING / / REPLACEMENT AND/OR GRINDING / / / /	
	AMPS OR INTERSECTIONS Intersection/driveway within 300 m upstream of sensor location Y / N distance Intersection/driveway within 300 m downstream of sensor location Y / N distance Is shoulder routinely used for turns or passing? Y / N	
9.	DRAINAGE (Bending plate and load cell systems only) 1 – Open to ground 2 – Pipe to culvert 3 – None	
	Clearance under plate6 in Clearance/access to flush fines from under system Y / N	

10. * CABINET LOC	ATION				
	Same side of road as LTPP lane $\underline{\mathbf{Y}}$ / N Median Y/ $\underline{\mathbf{N}}$ Behind barrier Y / N				
Distance from	edge of traveled lane31 ft				
	system 37 ft				
	3R				
11112	<u>JK</u>				
CADINETAC	CECC controlled by I TDD / CTATE / IOINT 9				
	CESS controlled by LTPP / STATE / JOINT?				
	t - name and phone number Roy Czinku 306-653-6627				
Alterna	te - name and phone number Joe Avis 916-654-3072				
44 de DOMIED					
11. * POWER					
	pinet from drop <u>10</u> ft Overhead / underground / solar /				
AC in cabinet?					
Service provid	er N/A Phone number				
12. * TELEPHONE					
Distance to cal	oinet from drop ftOverhead / underground / <u>cell</u> ?				
Service provid	er Phone Number				
1					
13.* SYSTEM (softw	rare & version no.)- <u>iSYNC_</u>				
	nection – RS232 / Parallel port / USB / Other				
Comparer Com	<u> </u>				
14 * TEST TRUCK T	TURNAROUND time6 min				
14. ILDI INCCK I	tora moon build thin				
15. PHOTOS	FILENAME				
Power source	06_0200_Solar_Panel_03_25_2008.jpg				
	06 0200 Solar Power Box 03 25 2008.jpg				
Phone source	06 0200 Cell Modem 03 25 2008.jpg				
Cabinet exterior	06 0200 Cabinet Exterior 03 25 2008.jpg				
Cabinet interior	06_0200_Cabinet_Interior_Front_03_25_2008.jpg				
Cuomet memor	06_0200_Cabinet_Interior_Rear_03_25_2008.jpg				
Weight sensors	06 0200 Leading WIM Sensor 03 25 2008.jpg				
Weight believis	06 0200 Trailing WIM Sensor 03 25 2008.jpg				
Classification sensors	00 0200 Training Why School 03 23 2000.jpg				
Other sensors	06_0200_Leading_Loop_03_25_2008.jpg				
Other sensors	06_0200_Trailing_Loop_03_25_2008.jpg				
Description Los					
Description Loc	*				
Downstream direction at sensors on LTPP lane					
<u>06_0200_Downstream_03_25_2008_jpg</u>					
-					
06_0200_Upstream_03_25_2008.jpg					

COMMENTS	None	
COMPLETED BY	Dean J. W	olf
PHONE 301-210-	5105	DATE COMPLETED 03 / 25 / 2 0 0 8

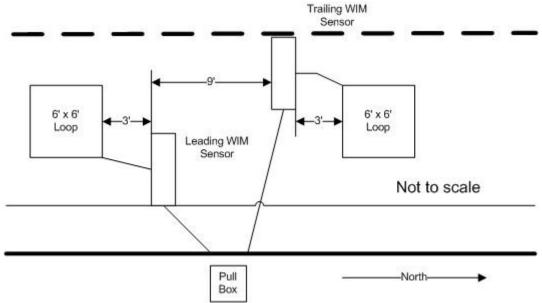


Figure 6-1 Sketch of Equipment Layout

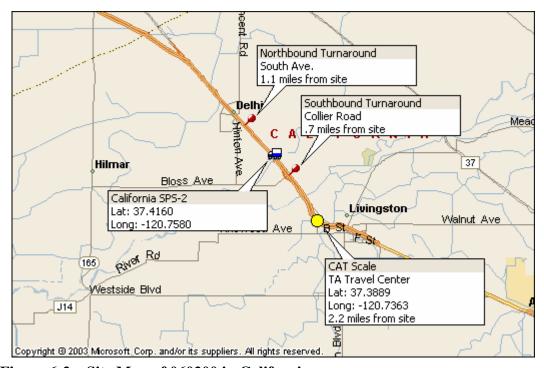


Figure 6-2 – Site Map of 060200 in California



Photo 1 06_0200_Upstream_03_25_2008 .jpg



Photo 2 06_0200_Downstream_03_25_2008.jpg



Photo 3 06_0200_Solar_Panel_03_25_2008.jpg



Photo 4 06_0200_Solar_Power_Box_03_25_2008.jpg



Photo 5 06_0200_Cell_Modem_03_25_2008.jpg



Photo 6 06_0200_Cabinet_Exterior_03_25_2008.jpg



Photo 7 06_0200_Cabinet_Interior_Front_03_25_2008.jpg



Photo 8 06_0200_Cabinet_Interior_Rear_03_25_2008.jpg



Photo 9 06_0200_Leading_Loop_03_25_2008.jpg



Photo 10 06_0200_Leading_WIM_Sensor_03_25_2008.jpg



Photo 11 06_0200_Trailing_WIM_Sensor_03_25_2008.jpg



Photo 12 06_0200_Trailing_Loop_03_25_2008.jpg

SHEET 18	STATE CODE	[6]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0200</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) 3/25/200	<u>8</u>

1.	DA	ATA PROCESSING –
	a.	Down load – State only LTPP read only LTPP download LTPP download and copy to state
	b.	Data Review – State per LTPP guidelines State – Weekly Twice a Month Monthly Quarterly LTPP
	c.	Data submission – State – Weekly Twice a month Monthly Quarterly LTPP
2.	ΕÇ	QUIPMENT –
	a.	Purchase – State LTPP
	b.	Installation − ☐ Included with purchase ☐ Separate contract by State ☐ State personnel ☐ LTPP contract
	c.	Maintenance – Contract with purchase – Expiration Date _5 years from installation Separate contract LTPP – Expiration Date Separate contract State – Expiration Date State personnel
	d.	Calibration – Vendor State LTPP
	e.	Manuals and software control – State LTPP
	f.	Power – i. Type – Overhead Underground Solar ii. Payment – State LTPP N/A

SHEET 18	STATE CODE	[6]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0200]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>3/25/2008</u>	

	g.	Communication –
		i. Type – ii. Payment –
		☐ Landline ☐ State ☐ LTPP
		Other N/A
3.	PA	AVEMENT –
	a.	⁷¹ —
		☑ Portland Concrete Cement☐ Asphalt Concrete
	b.	Allowable rehabilitation activities –
		☐ Always new ☐ Replacement as needed
		Grinding and maintenance as needed
		Maintenance only
		☐ No remediation
	c.	Profiling Site Markings – Permanent
		☐ Fermanent ☐ Temporary
4.	10	N SITE ACTIVITIES –
	a.	WIM Validation Check - advance notice required <u>2</u> ☐ days ☐ weeks
	b.	Notice for straightedge and grinding check - 2 ☐ days ☐ weeks
		i. On site lead −
		ii. Accept grinding –
		State
		□ LTPP
	c.	Authorization to calibrate site –
		☐ State only LTPP
	d.	
	u.	☐ LTPP – ☐ Semi-annually ☐ Annually
		☐ State per LTPP protocol – ☐ Semi-annually ☐ Annually
		State other –

SHEET 18	STATE CODE	[6]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0200]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>3/25/2008</u>	

	e.		Vehicles			
		i.	Trucks – 1st – <u>Air suspension 3S2</u> 2nd – <u>_3S2 different weigh</u> 3rd – <u></u> 4th – <u></u>	State t/suspension State State State	□ LTPP □ State □ LTPP □ LTPP	⊠ LTPP
		ii.	Loads –	State	□ ☐ LTPP	
		iii.	Drivers –	State	☐ LTPP	
	f.	Contr	ractor(s) with prior successful exp	erience in WIM	I calibration in	state:
	g.	Acces i.	ss to cabinet Personnel Access – State only Joint LTPP			
		ii.	Physical Access − Key Combination			
	h.	State	personnel required on site –	☐Yes ⊠No)	
	i.	Traffi	c Control Required –	☐Yes ⊠No)	
	j.	Enfor	cement Coordination Required –	☐Yes ⊠No)	
5.	SI'a.		ECIFIC CONDITIONS – s and accountability –			
	b.	Repor	rts –			
	c.	Other	·			
	d.	Speci	al Conditions –			
6.	CC	ONTAC	CTS –			
	a.	Equip	oment (operational status, access, o	etc.) –		
			Name: Roy Czinku	Phor	ne: <u>(306) 653-6</u>	627
			Agency: <u>IRD</u>			

SHEET 18	STATE CODE	[6]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0200</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) 3/25/200	<u>8</u>

, 15, (, , , , , , , , , , , , , , , , , , ,	
b.	Maintenance (equipment) – Name: Roy Czinku	Phone:(306) 653-6627
	Agency: <u>IRD</u>	
c.	Data Processing and Pre-Visit Data – Name: Roy Czinku	Phone:(306) 653-6627
	Agency: <u>IRD</u>	
d.	Construction schedule and verification –	
	Name: <u>Joe Ais</u>	Phone: 916-654-3072
	Agency: CalTrans	
e.	Test Vehicles (trucks, loads, drivers) –	
	Name:	Phone:
	Agency:	
f.	Traffic Control –	
	Name:	Phone:
	Agency:	
g.	Enforcement Coordination –	
	Name:	Phone:
	Agency:	
h.	Nearest Static Scale	
	Name: <u>CAT @ TA Livingston</u>	Location: SR-99 @ Winton
		Parkway Exit
	Phone:	

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[06]
*SHRP SECTION ID	[0200]

SITE CALIBRATION INFORMATION

1.	* DATE OF CALIBRATION (MONTH/DAY/YEAR)	[3/25/2008]
2.	* TYPE OF EQUIPMENT CALIBRATED W	ZIMCLASSIFIER X_BOTH
	* REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION X OTHER (SPECIFY) LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
4.	* SENSORS INSTALLED IN LTPP LANE AT THIS SI BARE ROUND PIEZO CERAMIC B. CHANNELIZED ROUND PIEZO LO CHANNELIZED FLAT PIEZO X II OTHER (SPECIFY)	TE (CHECK ALL THAT APPLY): ARE FLAT PIEZO _X_ BENDING PLATES OAD CELLS QUARTZ PIEZO NDUCTANCE LOOPS CAPACITANCE PADS
5.	EQUIPMENT MANUFACTURERIRD/ PAT Traff	<u>ic</u>
	WIM SYSTEM CAI	LIBRATION SPECIFICS**
6.**	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCAL	E (Y/N) <u>X</u> TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	
7.	SUMMARY CALIBRATION RESULTS (EXPRES MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW DYNAMIC AND STATIC SINGLE AXLES DYNAMIC AND STATIC DOUBLE AXLES	1.1 STANDARD DEVIATION
8.	3 NUMBER OF SPEEDS AT WHICH CALIB	RATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)	45 50 55
10.	CALIBRATION FACTOR (AT EXPECTED FREE	FLOW SPEED)3360
11.*	* IS AUTO-CALIBRATION USED AT THIS SITE? IF YES, LIST AND DEFINE AUTO-CALI	
	<u>CLASSIFIER</u>	TEST SPECIFICS***
12.*	** METHOD FOR COLLECTING INDEPENDENT V VIDEOX_ MANUAL	OLUME MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	T TIME _X NUMBER OF TRUCKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEHICL *** FHWA CLASS 9 0 *** FHWA CLASS 8 0	FHWA CLASS FHWA CLASS FHWA CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES:	FHWA CLASS
	RSON LEADING CALIBRATION EFFORT:Dean J. DNTACT INFORMATION:301-210-5105	Wolf, MACTEC rev. November 9, 1999
		· · · · · · · · · · · · · · · · · · ·

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[06]
*SHRP SECTION ID	[0200]

SITE CALIBRATION INFORMATION

1. * D	DATE OF CALIBRATION (MONTH/DAY/YEAR)	[3/26/2008]
2. * T	YPE OF EQUIPMENT CALIBRATED WI	MCLASSIFIER _X BOTH
~ ~ ~	EASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION OTHER (SPECIFY) LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
~- ~- ~-	ENSORS INSTALLED IN LTPP LANE AT THIS SIT BARE ROUND PIEZO CERAMIC BA CHANNELIZED ROUND PIEZO LO CHANNELIZED FLAT PIEZO X IN OTHER (SPECIFY)	TE (CHECK ALL THAT APPLY): RE FLAT PIEZO _X_ BENDING PLATES AD CELLS QUARTZ PIEZO DUCTANCE LOOPS CAPACITANCE PADS
5. EQ	UIPMENT MANUFACTURERIRD/ PAT Traffic	<u>:</u>
	WIM SYSTEM CALI	BRATION SPECIFICS**
6.**CA	LIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE	(Y/N) <u>X</u> TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	
7.	SUMMARY CALIBRATION RESULTS (EXPRESS MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW	.2 STANDARD DEVIATION0.7 .3 STANDARD DEVIATION 1.8
8.	3 NUMBER OF SPEEDS AT WHICH CALIBR	RATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)	45 50 55
10.	CALIBRATION FACTOR (AT EXPECTED FREE F	FLOW SPEED)3360
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (*) IF YES, LIST AND DEFINE AUTO-CALIB	
	<u>CLASSIFIER T</u>	EST SPECIFICS***
12.***	METHOD FOR COLLECTING INDEPENDENT VO	
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIMEX NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 <u>0</u>	FHWA CLASS FHWA CLASS FHWA CLASS
		FHWA CLASS
	ON LEADING CALIBRATION EFFORT: <u>Dean J. V</u> FACT INFORMATION:301-210-5105	Wolf, MACTEC rev. November 9, 1999



Sheet 19	*STATE_CODE 06
LTPP Traffic Data	* SPS PROJECT ID 0200
*CALIBRATION TEST TRUCK #_1 Rev. 08/31/01	* DATE 3/26/08
PART I.	TOUCK #28
1.* FHWA Class 2.* Number of Axles	
AXLES - units - lbsy 100s lbs / kg	
GEOMETRY	
8 a) * Tractor Cab Style - Cab Over Engine (Conventional	b) * Sleeper Cab? (Y)N
9. a) * Make: KENUSELY b) * Model:	
10.* Trailer Load Distribution Description:	
PALLETTZED WINGER LOADED	DYGO TORIGO
to now s	
— · · · · · · · · · · · · · · · · · · ·	d tenths C to D 321
D to E	E to F
Wheelbase (measured A to last)	Computed
13. *Kingpin Offset From Axle B (units) (+ is to th	
SUSPENSION	
A 75 R 24.5 2 FULL LEAF B 86 R 24.5 AIR C 80 R 24.5 AIR	
D 75R 225 AIR	
E 75R 22 S AIR	
F	

Sheet 19	* STATE_CODE 06
LTPP Traffic Data	* SPS PROJECT ID, 0200
*CALIBRATION TEST TRUCK #_1_	*DATE 3/2/58

PART II

Day 1

*b) Average Pre-Test Loaded weight

*c) Post Test Loaded Weight

77070

*d) Difference Post Test – Pre-test

-450

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	12020	16800	16800	15940	15940		77500
2	12020	16788	16780	15940	15940		77460
3							
Average	12-02-0	16790	16790	15940	15940		77480

Table 6. Raw data – Axle scales –

ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
<u> </u>							
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11920	16700	16700	15870	15870		77060
2	11680	16690	16690	15870	(5370		77000
3							
Average	11900	HVTOU	16700	15870	(5870		77030

AW 16695

16695

Measured By DEAN WOLF Verified By

		Sheet 19		* STATE_CODE 06				
		ΓΡΡ Traffic Data		* SPS PROJECT ID, 0200				
		IION TEST TRU	JCK # Ø	* 1	DATE 3/26/	<u>8</u>		
Rev. 08/31/01				Day 2	, ,			
7.2	*b) Average Pre-Test Loaded weight *c) Post Test Loaded Weight *d) Difference Post Test – Pre-test			76760 16390 370				
Table 5.2. R	law data – Ax	kle scales – pre	e-test					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
1	11880	16636	16635	15810	12810		76760	
2	11923	16623	16620	15800	15800		76760	
3								
Average	11200	16625	16625	15805	15805		76760	
Table 6.2. R	aw data – Ax	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
2								
3								
Average								
Table 7.2 Ra	nw data – Axl	e scales – posi	t-test					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
1	11780	16 550	16550	16750	15750		76 380	
2	11820	16520	(6520	15770	15770		76400	
3								
Average	11800	५६५७	4540	(5760	15760		76590	
	^	16535	16535 Ba)			,	
Measured By _	09M		Verified B	~~~) Y	Weight date	= 3/26/08	

	Sheet 19	* STATE_CODE 06			
	PP Traffic Data	* SPS PROJECT ID 0200			
*CALIBRATI v. 08/31/01	ION TEST TRUCK #_2_	* DATE 3/260/08			
ART I.		Thuck # 33 Theren # 128			
* FHWA Class	2.* Number of Axles	S Number of weight days			
XLES - units - (lbs) 10	00s lbs / kg				
EOMETRY					
· · · · · · · · · · · · · · · · · · ·	Cab Over Engine / Conventional				
a) * Make: FAG (CHT	UNEW b) * Model:				
).* Trailer Load Distribu	tion Description:	S.			
<u>Partest Peren</u>	WMBEN LOPPED S	VEN TANDEMS			
	(units):				
b). Trailer Tare Weight	t (units):	·····			
* Axle Spacing – units	m / feet and inches / feet ar	nd tenths			
to B <u>18.5</u>	B to C 42	C to D 32.0			
	D to E 4.3	E to F			
Wheelbase (measur	red A to last)	Computed			
3. *Kingpin Offset From	Axle B (units)				
	(+ is to t	he rear)			
USPENSION					
Axle 14. Tire Size	15.* Suspension Description (leaf, air, no. of leaves, taper or flat leaf, etc.)			
A 7512745	2 FULL LEP				
B <u>88 R 24.5</u>	A (R				
C 75 R 24.5					
D 11R 22.5					
E 11223					
F					

	Sheet 19	* STATE_CODE 06
	LTPP Traffic Data	* SPS PROJECT ID 0200
	*CALIBRATION TEST TRUCK #_2_	*DATE 3/26/06
-		

PART II

Day 1

*b) Average Pre-Test Loaded weight

*c) Post Test Loaded Weight

*d) Difference Post Test – Pre-test

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11980	13660	13060	13462	13460		65020
2	12000	13656	13056	/3460	19460		6502A
3							
Average	11990	13555	13055	13460	13460		65620

Table 6. Raw data – Axle scales –

Dass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11900	13010	13010	13450	13450		64850
2	11860	13030	(3030	13470	13470		64860
3							
Average	11580	13020	13020	13460	13460		CARAA

Weight date 3 - 25-08 Measured By DEAN WAF Verified By D

able 7.2 Rass	Axle A (1900 (1766	12980 13010 13000 12995pm	12980 13010 13000 12995	(3440 (3440 (3440	13440		64640 64660		
ass	11800	12980	12980	(3440 ()440	13440		64660		
	11800	12980	12980	13440	13440		64640		
	11800	12980	12980	13440	13440		64640		
	Axle A	Axle B	TAIL C			1	, ~ 1 11		
	ıw data – Axle		t-test Axle C	Axle D	Axle E	Axle F	GVW		
verage									
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW		
able 6.2. R	aw data – Axl								
verage	11910	13005	13005	13450	13450		6482		
		v _e							
	11900	13000	13000	13450	13450		64800		
	11920	13000	13010	13450	13450		64840		
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW		
able 5.2. F	taw data – Ax				~				
		t Loaded Wei ce Post Test -		64657	······································				
.2	•	Pre-Test Loa	_	4482					
				Day 2					
ev. 08/31/01						front in the second			
	~	PP Traffic Data TON TEST TRU			* SPS PROJECT ID 0200 * DATE 3/26/08				
00/21/01		Sheet 19				06			

Sheet 20	* STATE_CODE06_
LTPP Traffic Data	*SPS PROJECT_ID _0_2_0_0_
Speed and Classification Checks * of* _2	* DATE3 / _25 /

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class
69	605	34908	69		60	9	35016	60	9
56	IJ	34912	5°		58	9	35022	61	9
62	9	34721	<u>5)</u>	9	58	9	35027	59	9
62	9	34923	GO	9	ジ フ	9	35928	55	9
57	1 1	34927	54	} }	55	9	35039	573	9
57	9	34934	58	9	5 4	9	3 20 HI	5	9
62	5	34938	62	5	54	9	35649	54	9
56	9	349 <i>4</i> 7	58	2	54	9	35050	57	9
56	9	34948	58	2	66	<u> </u>	3505H	66	5
59		34952	. 65	5	55	1)	35060	53	/)
60	9	34953		9	5.5°	\$5	35067	55	5
57	3	34957	57	9	62-	7	35072	59	9
54	9	34960	58		62	6	35073	63	6
56	9	34961	56	9	57	9	35074	58	9
60	.9	34964	58	9	59	8	35575	60	3
59	2	34968	5 9	9	64	5	35083	43	5
57	9	34974	58	9	57	9	35087		9
539	10	34982	53	10	58	9	35089	56	9
58		34987	<i>5</i> 8	9	52	9	35092	5"5"	9
55	8	34990	2 Cf	8	55	9	3.5°98	55	9
59	9	34995	61	9		/)	3564	53	pt/)
Comment of the second	9	34998	59	9	57	9	35100	与中	g
60	9	35 5	62	9	57	9	35108	5	9
G7	S	35006	CC		55	9	35114	57	9
59	5	35010	60	9	56	.5	35/15	56	9

Recorded by MARK 3

Direction N Lane 1 Time from 1235PM to 1255PM



Sheet 20	* STATE_CODE	_06
LTPP Traffic Data	*SPS PROJECT_ID	_0_2_0_0
Speed and Classification Checks * of*	* DATE	3/25/08

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
SF	9	35)19	58	9	5)	9	35234	55	9
56	8	35122	54	স্থ	55	9	35745	5 ^T e	3
58	9	35138	60	9	54	5	35246	54	5
55	9	35144	6 55	9	58	9	35252	- 62	9
57	9	35150	57	g	60	Annual Control	35241	62	5
62	9	35153	61	9	59	//	35267	41	5 11
53	g	25155	54	8	56	9	3522	5 54	# 9
56	9	35159	54	A 9	57	9	35280	57	9
3	9	35167	58	9	61	9	3528)	61	9
60	9	35168	58	9	57	2	352 8 9	57	9
58	5	35174	55	5	57	7	35301	5)	8
5°8	5	35175	58	5	<i>5</i> 7	8 8	353/1	55	8
57	9"	35/82	61	<i>J</i>	56	9	35315	55	9
57	المراوية والمراوية و	35185	33	/ \	59	.8	35318	59	#8
5)	2,	35188	58	5	37	9	35319	57	9
3 5	9	35194	56	9	55	8	35320	53	B
55	9	35195	55	9	Ste	9	35326	52	5
57		3572=1	57	/1	55	9	35327	555	9
56	9	3 <i>52</i> s 2	54	9	57	//	3 <i>5322</i>	Secretary Marie Cons. Secretary American	/)
574	9	3525	55	2	62	5	35336	65	5
57	9	35220	J 9	5	53	2	3 <i>5</i> 340	5	9
51	5	35226	SÓ		58	57	35344		9
64	lo	35227	64	10	58	diment	35348	<u>58</u>	9
<i>57</i>	11	35231	55	/1	5 5	9	3949	55	9
55	8	35232	55	્ર	54	9	35351	53	9

Recorded by MADK 2

Direction N Lane 1 Time from 2551 to 1:14pm



Sheet 20	* STATE_CODE	_0_6_
LTPP Traffic Data	*SPS PROJECT_ID	_0_2_0_0_
Speed and Classification Checks * of* _2_	* DATE <u>3 / 26</u>	/ <u>8</u> 2

WIM speed	WIM	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
6-	9	49290	60	9	54	Em-	49374	54	500
59	9	49295	58	9	53	2	49375	SЭ	9
57	9	49236	55	9	55	9	49379	55	3
43	9	4929 8	63	9	56	8	42380		8
57	8	49361	55	8,	60 100	9	49390	60	2
65	5	49307	45	5	59	9	49392	59	9
62	9	40358	63	9	56	9	49396	56	9
57	8	49310	57	8	58	9	49412	<i>5D</i>	9
66	5	49313	65	5	<i>I</i> 8	9	40413	58	9
<u> </u>	9	493 9	63	9	57	9	49416	57	
59	9	49321	60	C.S.	62	9	4942]	61	9
2	9	49323	5 B	9	55	9	49428	61	9
	8	49327	<i>(</i> 9	8	50	9	49429	61	9
62	9	49328	62	9	58	9	49432	55	2
58	9	49334	60	9	55	9	49435	56	9
59	9	49335	5 9	8 9	57	6	49439	57	6
<i>Ç</i> 2	5	49342	63	5	58	Ço	49443	6)	6
60	4	42348	65	4	56		49449	55	9
60	G	42347	6)	Ġ	5	9	49450		9
55	9	49348	Control of Section	9	59	9	49454	59	9
55	9	45345	.5TY	9	62	5	49455	62	Parage Language Language
	9	49354	And has	9	57 100	3	49459	58	9
.58	8	49358	Egy Fey	8	62	9	49461	62.	9
59	9	49359	E B	9	59	Co	49462	60	6
58	8	49368	و المار	8	57	5	40469		5

Recorded by MARK 2 Direction M Lane 1 Time from 1:23 PM to 1:37 PM



Sheet 20	* STATE_CODE _0_6_
LTPP Traffic Data	*SPS PROJECT_ID _0_2_0_0_
Speed and Classification Checks * 2 of* 2	*DATE3/ <u>26/</u> 08

WIM speed	WIM	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
56	8	49483	60	8	60	9	49597	60	9
56	9	49485	59	9	54	9	496-2	53	9
54	8	42420	57	8	52	9	496=3	53	9
55	9	49496	55	9	56	9	49609	58	9
59	5	49500	<u> </u>	5	54	øi)	49612	56	#/)
54	9	49524	54	9	59	9	49625	60	9
57	g	49510	56	9	60	8	49622	57	8
55	9	49517	62	9	57	9	49628	59	9
54	9	49522	54	9	55	9	49629	54	9
57	9	49526	54	2	55	9	49636	53	9
60	9	49528	62	9	55	8	49641		8
59	9	49533	53	9	57	9	49649	59	9
54	8	49537	53	8 8	53	9	49667	60	9
.58	9	49541	55	Ĵ	55	9	49668	54	9
55	9	49542	54	9	56	9	40672	54	9
57	9	49545	54	9	57	7	49685	59	8
52	9	49555	59	9	59	C.C.M.	49688	58	2
43	5	49560	C-2	5	59	9	49691	61	9
61	9	49570	Com	Ï	64		49693	62	5
57	5	49573	54	5	60	9	49694	63	9
53	9	49586	Ges	2	guer runs	9	49697	59	3
58	5	49582	59		57	9	49698	58	
58	9	49575	58		5 9	9	40702	So (
55	9	40536	5.5	9	60	9	49706	58	9
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Sheet 21	LTPP Traffic Data	WIM System Test Truck Records 2 of 3

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Sheet 21	LTPP Traffic Data	WIM System Test Truck Records 2 of 3
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E-F space														
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Axle B weight.	1. 3		18/8		28/82	69/3	28/62	3	28/58	57/29			:	
Axle A weight.	63/20	5/2	78	57/s	20/20	29/0	61/28	28/	03/10	19/65				
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Axle C weight.	8%))	84/78	200	1	77/28	C3/62	8%	18/38	62	30	200	35/20	200	273	15 TO	0/20
Axle B weight.	57		6	18/83/	Co.	23/62	10%)	89/	19/2	2/8	2000	78/98	20		88/81	63
Axle A weight.	58/3	200	23/28	63/S	3	To the second	19/65	00	2007	25/67	200	59/cs	2000	5/58	25/29	N. S.
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Pass	<i>0.</i> /	2)	0	<u>.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,</u>	- Intervention Intervention	Torona Edu	4	4	(A)	~	<i>J</i>	oresenta.	<u>v</u>	Ŋ	2	1 Section 1
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E-F space															
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Axle F weight														:	
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Axle D weight.	72	78	200	7163	87/2	12	7637	No.	<u> </u>				7-7-7-8-7-7-7-7-7-7-7-7-7-7-7-7-7-7-7-7		>
Axle C weight.	7.2%	62/	85/38	67/66	58/28		63/63	27/33	p.s.						
Axle B weight,	36/85	59/63	164 89/3	EH2	102		(17%)	70%					000		
Axle A weight.	65/	27/65	59/64	C3/63		16 (Sep.)	30	10%							
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TEST VEHICLE PHOTOGRAPHS FOR SPS WIM VALIDATION

March 25-26, 2008

STATE: California

SHRP ID: 060200

Photo 1 06_0200_Truck_1_Tractor_03_25_2008.jpg	2
Photo 2 06_0200_Truck_1_Trailer_03_25_2008.jpg	
Photo 4 06_0200_Truck_1_Suspension_2_03_25_2008.jpg	
Photo 5 06_0200_Truck_1_Suspension_3_03_25_2008.jpg	
Photo 6 06_0200_Truck_2_Tractor_03_25_2008.jpg	
Photo 7 06_0200_Truck_2_Trailer_03_25_2008.jpg	
Photo 8 06_0200_Truck_2_Suspension_1_03_25_2008.jpg	
Photo 9 06_0200_Truck_2_Suspension_2_03_25_2008.jpg	
Photo 10 06 0200 Truck 2 Suspension 3 03 25 2008.jpg	



Photo 1 06_0200_Truck_1_Tractor_03_25_2008.jpg



Photo 2 06_0200_Truck_1_Trailer_03_25_2008.jpg



Photo 3 06_0200_Truck_1_Suspension_2_03_25_2008.jpg



Photo 4 06_0200_Truck_1_Suspension_3_03_25_2008.jpg



Photo 5 06_0200_Truck_2_Tractor_03_25_2008.jpg



Photo 6 06_0200_Truck_2_Trailer_03_25_2008.jpg



Photo 7 06_0200_Truck_2_Suspension_1_03_25_2008.jpg



Photo 8 06_0200_Truck_2_Suspension_2_03_25_2008.jpg



Photo 9 06_0200_Truck_2_Suspension_3_03_25_2008.jpg

ETG LTPP CLASS SCHEME, MOD 3

Axle 1 Weight Min *			-			2.5				2.5	3.5	3,5			2.5	3.5	3.0	3.5		2.5	3.5	5.0	3.5	3.5	3.5	5.0	5.0	5.0	5.0	5.0
Gross Weight Min-Max		0.10-3.00	1.00-7.99	1.00-7.99	12.00 >	8.00 >	1.00-11.99	1.00-11.99	20.00 >	12,00-19,99	12.00 >	20.00 >	1.00-11.99	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20,00 >	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20.00>	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00>	20.00 >
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Spacing 5						700000000000000000000000000000000000000																				2.50-10.99	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 4																			1.00-11.99	1.00-11.99	2.50-6.30	2.50-11.99	12.00-27.00	2.50-6.30	11.00-26.00	2.50-11.99	6.00-24.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 3			7,000,000										1.00-11.99	1.00-11.99	1.00-20.00	2.50-12.99	13.00-50.00	2.50-20.00	1.00-11.99	1.00-25.00	2.50-6.29	6.30-65.00	6.30-50.00	2.50-6.30	6.00-20.00	6.10-50.00	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 2							6.00-25.00	6.00-25.00	3.00-7.00	6.30-30,00	2.50-6.29	11.00-45.00	6.00-30.00	6.00-30.00	6.30-40.00	2.50-6.29	2.50-6.29	8.00-45.00	6.00-25.00	6.30-35.00	2.50-6.29	2.50-6.29	2.50-6.29	16.00-45.00	11.00-26.00	2.50-6.30	2.50-6.30	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 1		1.00-5.99	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00 - 10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-23.09	6.00-23.09	6.00-10.10	10.11-23.09	6.00-26.00	6.00-23.09	6.00-26.00	6.00-26.00	10.11-23.09	6.00-23.09	6.00-23.09	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-26.00	6.00-26.00	6.00-45.00	6.00-45.00	6.00-45.00
No. Axles		7	7	2	2	2	3	3	3	3	3	3	4	4	#	4	4	4	ĸ	\$	S.	w.	\$	5	S	9	9	r-	90	6
Vehicle Type	7	Motorcycle	Passenger Car	Other (Pickup/Van)	Bus	2D Single Unit	Car w/ I Axle Trailer	Other w/ 1 Axle Trailer	Bus	2D w/ 1 Axle Trailer	3 Axle Single Unit	Semi, 2S1	Car w/2 Axle Trailer	Other w/ 2 Axle Trailer	2D w/ 2 Axle Trailer	4 Axle Single Unit	Semi, 3SI	Semi, 2S2	Other w/ 3 Axle Trailer	2D w/3 Axle Trailer	5 Axle Single Unit	Semi, 3S2	Truck+FullTrailer (3-2)	Semi, 2S3	Semi+FullTrailer, 2S12	Semi, 3S3	Semi+Full Trailer, 3S12	7 Axle Multi's	8 Axle Multi's	9 Axle Multi's
Class			7	60	4	S	7	60	4	'n	9	∞	7	3	S	-	%	×	3	w		6	6	6	=	10	12	13	13	3

Spacings in feet Weights in kips (Lbs/1000)
* Suggested Axle 1 minimum weight threshold if allowed by WIM system's class algorithm programming

System Operating Parameters

California SPS-2 (Lane 1)

Calibration Factors for Sensor #1

March 26, 2008
3395
3395
3420
3360
3360

Calibration Factors for Sensor #2

Validation Visit	March 26, 2008
80 kph	3395
88 kph	3395
96 kph	3420
105 kph	3360
112 kph	3360